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## The Swedish approach to modern technology in driver's education and testing

Olof Stenlund  
Swedish Transport Agency

# Overview

- Introduction
- What we should focus on right now
- What we are doing now, and what we can do in the near future regarding:
  - driver training
  - driving tests
- Examples of challenges in the near future

# Introduction

- Self-driving vehicles are coming (probably not in the way many believe)
- It's a long way to go, before self driving cars can be realized on the open market
- Ordinary passenger cars will gradually become more and more automated, and able to drive themselves in specific areas, in good conditions
- The hype of self-driving vehicles, has held back the debate on driver support systems (ADAS)
- We should talk about what different ADAS- functions can handle, and not what SAE-level they belong to

# What we should focus on right now

- We have until now talked a lot about what will happen in the future,
  - but now we need to start from what's here and now.
- It's better to first focus more on the oncoming advanced driver-assistance systems, and talk less about self-driving cars.
  - Focus on ADAS (especially those who can do parts of the dynamic driving task)



# What we should focus on right now

- It's most important to inform about the systems' limitations and new risks that arise

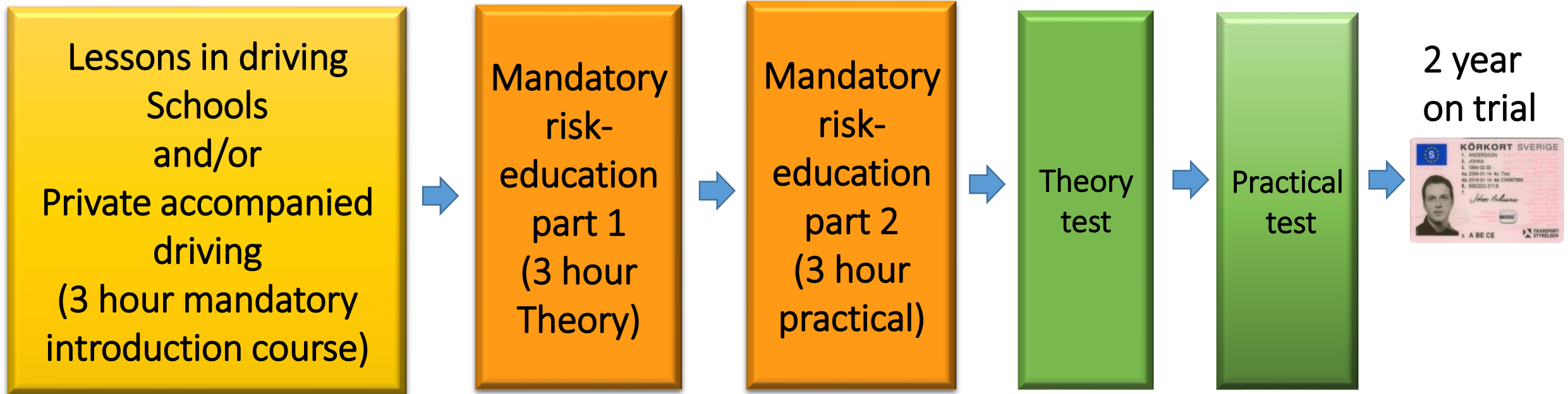


- ADAS will come in cheaper cars, and people will use it....
- We must ensure that ADAS is involved in driver training and in the test

# Examples of challenges in driver training?

- Many want's, and also choose to be available at all times  
*-I know it's dangerous, but I check the cell phone anyway when I drive“*
- We can point out that you should do this or that, introduce more rules, add more responsibilities etc. But...
- It is about human beings, it's difficult to control behavior, humans can decide themselves regardless of rules...
- It is important to get them to understand that, if you shall use this systems - do it in a responsible way, do it in appropriate places...

# Simplified view of the Swedish system for drivers education and examination, category B 2019





# Examples of current sub-goals in curriculum of the mandatory risk education

## **Theoretical sub goal**

The learner should have knowledge of:

- the importance of different technical support systems for safety, and how the systems can influence the driver's behavior

## **Practical sub goal**

The learner shall experience and realize:

- advantages, limitations and risks with different technical support systems

# Examples of some strategic principles in the practical risk education

- Based on common accidents
- Work with the causes of the accidents
- Show consequences of the accidents
- Focus should be on avoiding emergency situations, more than managing them
- The practical exercises must be such that the learner gets the experiences and discussions that allows him to make his own conclusions,
  - conclusions which are needed to achieve different sub-goals in the curriculum
- Important to experience failure caused by increased speed or distraction
  - The student must fail to avoid becoming over confident
- Coaching instead of teaching to succeed



# Examples of what we can do in the mandatory risk education, in the near future

- Provide knowledge about what the systems can do, and **what they can't do** (the ADAS systems limitations)
- Develop exercises with the aim of reducing the risk of over faith on the systems' capacity
- Create specific **motivational exercises** aimed to get them to understand to use this systems in a responsible way in appropriate places
- E.g. let them **experience**:
  - what can happen when using Adaptive Cruise Control combined with auto steering functions if a critical situation arises.
  - what happens when lane markings suddenly disappears in a curve or roadwork
  - limitations on slippery road conditions etc.

# **Possible content in risk education when these systems become more common**

**We can develop exercises to let the learners experience:**

- failures caused by lack of situational awareness,
- difficulties with situational recovery and emergency responding

**Challenge in the near future**

- To get enough time for the risk education
- To ensure the teachers competence

(We have good possibilities because we have introduced mandatory yearly further education for the teachers)



# What we are doing now and we can do in the near future regarding the Theory test

- Knowledge about different technical support systems can be measured in the theoretical test (e.g. advantages, limitations and risks)
- What's being tested, will be included in the education.  
“- What we test is what we get”
- The challenge is to construct relevant questions based on facts
- We will construct questions and put them in the theory test as soon as the different systems become more common on the market



# What we are doing now and we can do in the near future regarding the driving test

- We do not want to hinder the use and the development of new technology or new equipment
- We have only one rule for this issue in the regulations for driving tests:

*§ The examiner may decide that the use of technical support systems in the vehicle shall be limited, if it's necessary for any part of the assessment in the driving test.*

# What does the rule mean?

- It's ok to use all assistance systems, (e.g. Adaptive Cruise Control and Lane keep Assist)
- **but** the examiner can require that the candidate must be able to drive manual as well - the **examiner decides** what he or she need to see at each test
- It's a simple rule that lasts over time
- Easy to adapt to developments of new and still unknown technology
- Note: The use of ADAS can also lead to a failed driving test.  
E.g. Auto Emergency Braking (AEB) during driving

# Challenges and possible content in future driving test

- Vehicles used in the test should be representative for most of the cars

When a larger proportion of the vehicle fleet has ADAS (note: we are not there yet):

- Then we can implement some parts as mandatory to use in the driving test  
E.g. we could require use of Adaptive Cruise Control or “Highway pilot”.
  - as a first step if it’s present in the car

A bit further ahead in the future:

- the examiner might tell the candidate to hand over the driving task to the vehicles system when entering a highway or a rural road. And later take back control over the driving again if the system asks for it, or to exit the highway.
- Distracting tasks can also be included
- As a result it would be trained before the test

# Examples of other challenges in the near future

- Keep examiners updated and competent enough to cope with new technologies and difficulties that arise
  - We have possibilities in the periodic training (set in the DLD)
- We need to create harmonized international regulations including "self-driving" functions
  - The rules should be general formulated and not detailed, in order to last a long time.
  - As ADAS constantly develops, detailed rules quickly can be out of date
- How do we reach consumers who already holds a driving license and give them information about the systems limitations?

# Summary

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- ✓ Examples of challenges in the near future



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**Thank you for you attention!**

[Olof.Stenlund@transportstyrelsen.se](mailto:Olof.Stenlund@transportstyrelsen.se)